

Py*: A Formalization of Python's Execution Machinery



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Overview

- Motivation
- Research Contribution
- Typing Rules
- Evaluation Rules
- Discussion and Future Work
- Q & A

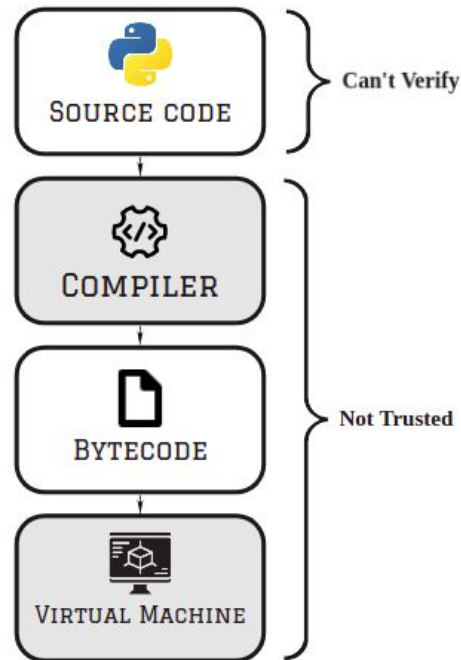


Motivation



Challenges of Formalizing Python

- Python was not designed with formal rigor.
- The language extends and grows very fast.
- **Formality:** Python source code doesn't have formal semantics.
- **Extendability:** It is hard to keep track with all different components.





Example of Python's Informality

Documentation:

“Non-identical instances of a class normally compare as non-equal unless the class defines the `__eq__()` method or the `__cmp__()` method”

Reality:

```
class Car():
    pass

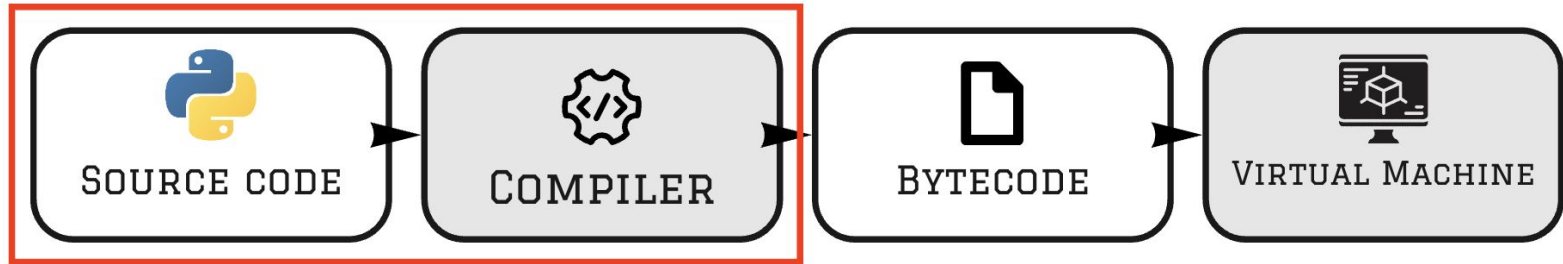
a = Car()
b = Car()

if a.__eq__(b):
    print("SHOULD NOT HAPPEN")
```

Reason:

- `a.__eq__(b)` returns `NotImplemented`
- `NotImplemented` has a Boolean value of `True`

● Previous Formalization Attempts



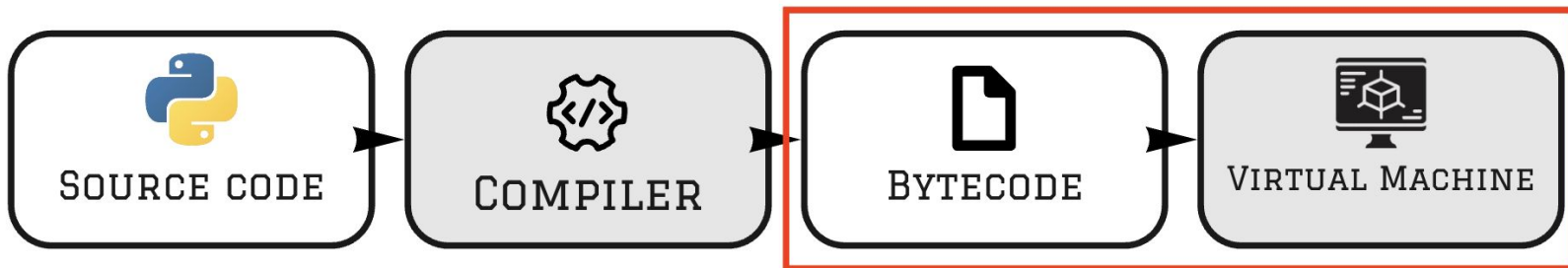
- Previous work focus on formalizing Python's Source code.
 - Forces them to handle very high-level concepts that hide a lot of complexities underneath.



Research Contribution



Focus on Bytecode



- Why?
 - **Simpler** and **smaller** set of instructions.
 - More stable than Source code which implies **easier extendability**.
 - **It's what gets executed at the end.**



Contribution

- **Bytecode formal semantics**
 - Formal semantics for typing and evaluation rules.
 - The system can be **extended** with rules for built-in classes.
 - **Safety** by proving progress and preservation.
- **Py***
 - A formally verified implementation of the rules in **F***.
- **Formally Verified Python Virtual Machine**
 - Finally we extract a formally verified executable OCaml code of Py*.

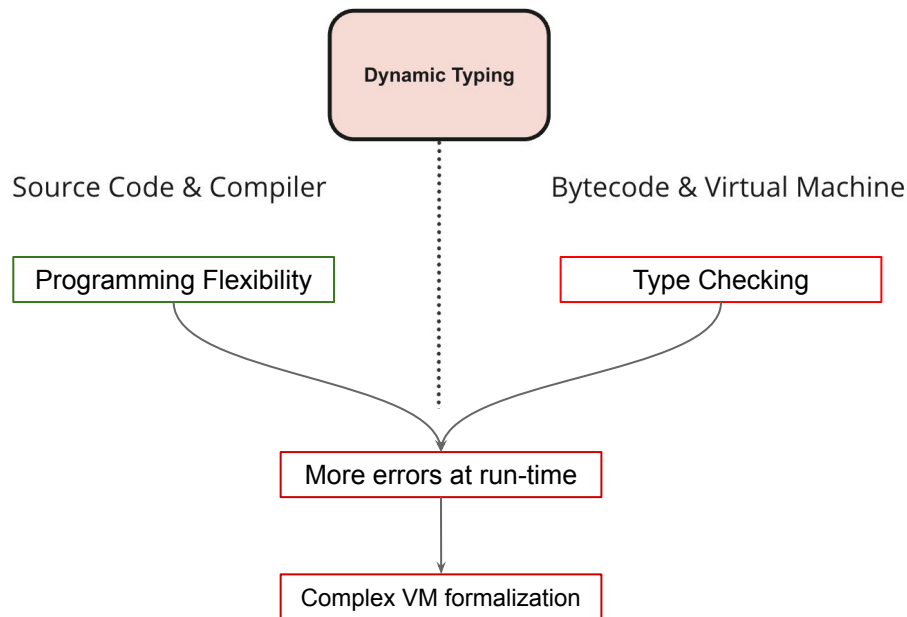


Typing



Challenges

- Python is a dynamically typed object-oriented language:
 - All entities in a python program have the same type called *object*.
 - At the source code level Python is *Statically uni-typed*.





Goals

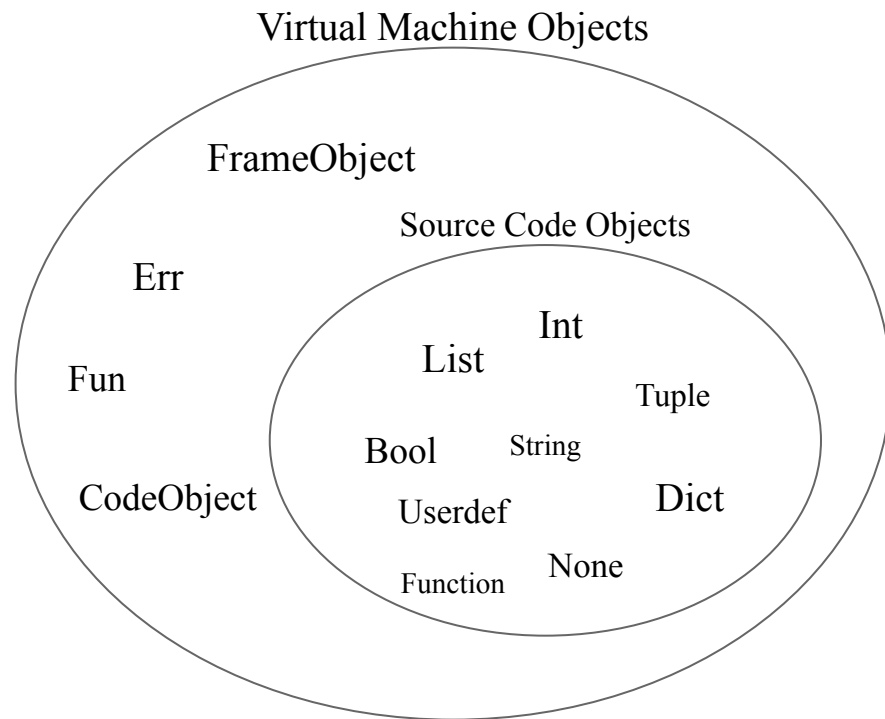
To maintain flexibility and ease of programming in Python while having the safety guarantees that we usually have with Static typing.

To ensure practicality by having a modular and extendable design for the typing system.



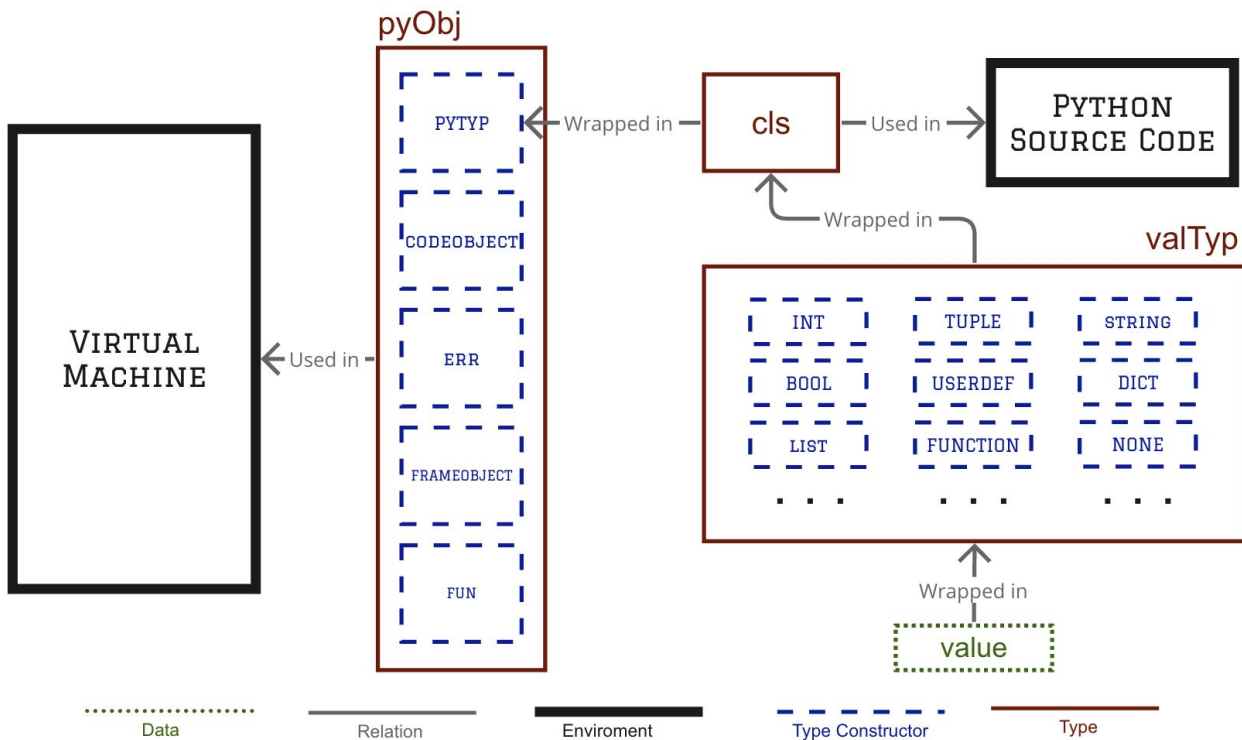
Program Entities

- To ensure modularity and safety:
 - Separate Source code Objects away from VM objects.
 - Define an interface that formalizes the interactions between Source Code Objects and VM Objects.
 - Entails:
 - If new objects are added then nothing that was already built breaks.





Typing System Design





Definitions of Program States

- Py* Functions on Frames which behaves as a program states.

Definition 3.1 (Frame). A frame is a tuple $\langle \varphi, \Gamma, i, \Delta \rangle$ where:

| | | |
|---|---|--|
| $\varphi \triangleq \langle \Sigma_g, \Sigma_l, \Sigma_{l_+} \rangle$ | : | Contexts $\triangleq \langle \text{global names, local names, local+}^1 \rangle$ |
| $\Gamma \triangleq \langle \Pi, \Sigma_c, \Sigma_v, \Sigma_n \rangle$ | : | Code Object $\triangleq \langle \text{bytecode, constants, varnames, names} \rangle$ |
| i | : | Program Counter |
| Δ | : | Data Stack |

| | | | |
|---|---|--|---|
| $\frac{obj : cls}{PYTYP(obj) : pyObj}$ | $\frac{co : codeObj}{CODEOBJECT(co) : pyObj}$ | $\frac{msg : str}{ERR(msg) : pyObj}$ | |
| $\frac{f : frameObj}{FRAMEOBJECT(f) : pyObj}$ | $\frac{f : list\ pyObj \rightarrow valTyp}{FUN(f) : pyObj}$ | $\frac{val : valTyp}{createObj(val) : pyObj}$ | |
| | | | |
| $\frac{name : str \quad pid : int \quad value : valTyp \quad fields : Map\ str\ pyObj \quad methods : Map\ str\ pyObj}{\{name, pid, value, fields, methods\} : cls}$ | | | |
| | | | |
| $\frac{}{USERDEF : valTyp}$ | $\frac{i : int}{INT(i) : valTyp}$ | $\frac{s : str}{STRING(s) : valTyp}$ | $\frac{b : bool}{BOOL(b) : valTyp}$ |
| $\frac{l : list\ cls}{LIST(l) : valTyp}$ | $\frac{t : list\ cls}{TUPLE(t) : valTyp}$ | $\frac{d : list\ (cls * cls)}{DICT(d) : valTyp}$ | $\frac{s : str}{EXCEPTION(s) : valTyp}$ |
| | $\frac{s : list\ cls}{SET(s) : valTyp}$ | ... $\frac{f : float}{FLOAT(f) : valTyp}$ | |
| | | | |
| $\frac{\varphi \triangleq \langle \Sigma_g, \Sigma_l, \Sigma_{l^+} \rangle : (Map\ str\ pyObj * Map\ str\ pyObj * list\ pyObj) \quad \Gamma : codeObj \quad i : int \quad \Delta : list\ pyObj}{\langle \varphi, \Gamma, i, \Delta \rangle : frameObj}$ | | | |
| $\frac{\Pi : list\ bytecode \quad \Sigma_c : list\ pyObj \quad \Sigma_v : list\ str \quad \Sigma_n : list\ str}{\langle \Pi, \Sigma_c, \Sigma_v, \Sigma_n \rangle : codeObj}$ | | | |

Fig. 2. Typing Rules for Python Objects


```

type opcode = | NOP: opcode
              | POP_TOP: opcode
              | ROT_TWO: opcode
              | ROT_THREE: opcode
              ...

type bytecode =
  | CODE: list opcode -> bytecode

type valTyp = | INT: int -> valTyp
              | STRING: string -> valTyp
              | BOOL: bool -> valTyp
              | LIST: list cls -> valTyp
              ...

and cls = {
  name: string;
  pid: int;
  value: valTyp;
  fields: Map.t string pyObj;
  methods: Map.t string pyObj
}

and pyObj =
  | PYTP: cls -> pyObj
  | CODEOBJECT: codeObj -> pyObj
  | FUN: (list cls -> builtins) -> pyObj
  | FRAMEOBJECT: frameObj -> pyObj
  | ERR: string -> pyObj

and codeObj = {
  co_code: bytecode;
  co_consts: list pyObj;
  co_varnames: list string;
  co_names: list string;
  co_cellvars: list string;
}

and frameObj = {
  dataStack: list pyObj;
  fCode: codeObj;
  pc: nat;
  f_localplus: list pyObj;
  f_globals: Map.t string pyObj;
  f_locals: Map.t string pyObj;
  f_cells: Map.t string pyObj;
  f_idCount: nat;
  f_usedIds: Map.t hashable nat
}

type vm = {
  callStack: list frameObj;
  code: codeObj;
  vmpid: nat;
  idCount: nat;
  usedIds: Map.t hashable nat
}

```

Fig. 5. Types in F★



Evaluation



Understanding Evaluation

- To understand how the Python's VM executes compiled bytecode, we used:
 - Python's bytecode documentations.
 - Investigated cpython source code whenever there were doubts.
- The challenge of english written documentations also appeared to exist in bytecode's documentations.
- cpython is is generally accepted as Python's reference implementation.



Evaluation Rules

- The rules formalize how frames are evaluated and how the frame stack is managed.
- The frame stack has two state:
$$\begin{array}{ll} K \triangleright f & : \text{Evaluation state} \\ K \triangleleft \text{ret}(v) & : \text{Return state} \end{array}$$
- We start by *Evaluation State*:
 - During that state, the top frame f is evaluated until it becomes $\text{ret}(v)$.
- Once this happens:
 - Switch to *Return State*, which does one of the following:
 - Return the value v to the caller frame (top frame).
 - Spawn a new frame.
 - End evaluation and return v if the frame stack is empty ϵ .
- The evaluation of the frame stack uses the judgment $K \rightarrow K'$, where K and K' are frame stacks.
- The evaluation of frames uses the judgment $f \xrightarrow{\Gamma, \Pi[i]} f'$, where f and f' are frames, and the arrow is labelled with the bytecode operation that is being executed.



Frame Stack Semantics

- Describe how the frame stack is managed and how frames interact with each other (i.e. data flow between frames).

$$\frac{\langle \varphi, \Gamma, i, \Delta \rangle \xrightarrow{\Gamma.\Pi[i]} \langle \varphi_n, \Gamma_n, i_n, \Delta_n \rangle}{K \triangleright \langle \varphi, \Gamma, i, \Delta \rangle \mapsto K \triangleright \langle \varphi_n, \Gamma_n, i_n, \Delta_n \rangle} \quad (1)$$

$$\frac{\langle \varphi, \Gamma, i, \Delta \rangle \xrightarrow{\Gamma.\Pi[i]} \text{ret}(\langle \varphi_n, \Gamma_n, i_n, \Delta_n \rangle)}{K \triangleright \langle \varphi, \Gamma, i, \Delta \rangle \mapsto K \triangleleft \text{ret}(\langle \varphi_n, \Gamma_n, i_n, \Delta_n \rangle)} \quad (2)$$

$$\frac{}{K \triangleleft \text{ret}(\langle \varphi, \Gamma, i, \langle \varphi_n, \Gamma_n, i_n, \Delta_n \rangle :: \Delta \rangle) \mapsto K; \langle \varphi, \Gamma, i + 1, \Delta \rangle \triangleright \langle \varphi_n, \Gamma_n, i_n, \Delta_n \rangle} \quad (3)$$

$$\frac{v \neq \text{FRAMEOBJECT}(_)}{K; \langle \varphi_p, \Gamma_p, i_p, \Delta_p \rangle \triangleleft \text{ret}(\langle \varphi, \Gamma, i, v :: \Delta \rangle) \mapsto K \triangleright \langle \varphi_p, \Gamma_p, i_p, v :: \Delta_p \rangle} \quad (4)$$

$$\frac{v \neq \text{FRAMEOBJECT}(_)}{\epsilon \triangleleft \text{ret}(\langle \varphi, \Gamma, i, v :: \Delta \rangle) \mapsto \text{final}(v)} \quad (5)$$

Fig. 3. Instructions for managing the frame stack



Frame Semantics

- Execute the code object inside a frame.
- Examples:

$$\frac{i < 0 \quad \text{or} \quad |\Gamma.\Pi| \leq i}{\langle \varphi, \Gamma, i, \Delta \rangle \xrightarrow{\Gamma.\Pi[i]} \text{ret}(\langle \varphi, \Gamma, i + 1, \text{ERR}(\text{"Program counter is out of bounds"}) :: \Delta \rangle)}$$

$$\frac{}{\langle \varphi, \Gamma, i, \text{ERR}(s) :: \Delta \rangle \xrightarrow{\Gamma.\Pi[i]} \text{ret}(\langle \varphi, \Gamma, i, \text{ERR}(s) :: \Delta \rangle)}$$

$$\frac{}{\langle \varphi, \Gamma, i, v :: \Delta \rangle \xrightarrow{\Gamma.\Pi[i]=\text{RETURN_VALUE}} \text{ret}(\langle \varphi, \Gamma, i, v :: \Delta \rangle)}$$



Frame Semantics

$$\frac{}{\langle \varphi, \Gamma, i, v :: \Delta \rangle \xrightarrow{\Gamma.\Pi[i]=\text{POP_TOP}} \langle \varphi, \Gamma, i + 1, \Delta \rangle}$$

$$v = \text{CODEOBJECT}(\bar{c}o) \quad f = \langle \langle \varphi.\Sigma_g, \{\}, [v_n, \dots, v_1] \rangle, \bar{c}o, 0, [] \rangle$$

$$\frac{}{\langle \varphi, \Gamma, i, v_1 :: \dots :: v_n :: v :: \Delta \rangle \xrightarrow{\Gamma.\Pi[i]=\text{CALL_FUNCTION}(n)} \text{ret}(\langle \varphi, \Gamma, i, f :: \Delta \rangle)}$$

$$\text{getMethod}(\text{floordiv}, v_2) = \text{FUN}(f) \quad f([v_2, v_1]) = \text{VALTYP}(v') \quad u = \text{createObj}(\text{VALTYP}(v'))$$

$$\frac{}{\langle \varphi, \Gamma, i, v_1 :: v_2 :: \Delta \rangle \xrightarrow{\Gamma.\Pi[i]=\text{BINARY_FLOOR_DIVIDE}} \langle \varphi, \Gamma, i + 1, u :: \Delta \rangle}$$



Objects Extendability

$\text{getMethod}(\text{floordiv}, v2) = \text{FUN}(f) \quad f([v2, v1]) = \text{VALTYP}(v') \quad u = \text{createObj}(\text{VALTYP}(v'))$

$\langle \varphi, \Gamma, i, v1 :: v2 :: \Delta \rangle \xrightarrow{\Gamma.\Pi[i]=\text{BINARY_FLOOR_DIVIDE}} \langle \varphi, \Gamma, i + 1, u :: \Delta \rangle$

- What is f ?

$$\frac{\text{obj} = \text{PYTYP}(\text{clsObj}) \quad v = \text{clsObj}.value}{\text{getValue}(\text{obj}) = v}$$

.....

$$\frac{\text{getValue}(v1) = \text{INT}(\bar{v}1) \quad \text{getValue}(v2) = \text{INT}(\bar{v}2) \quad \bar{v}1 \neq 0 \quad v' = \bar{v}2 / \bar{v}1}{\text{floordiv}([v2, v1]) = \text{INT}(v')}$$
$$\frac{\text{getValue}(v1) = \text{INT}(\bar{v}1) \quad \text{getValue}(v2) = \text{INT}(\bar{v}2) \quad \bar{v}1 = 0}{\text{floordiv}([v2, v1]) = \text{ERR}(s)}$$
$$\frac{\text{getValue}(v1) = \text{BOOL}(\bar{b}1) \quad \text{getValue}(v2) = \text{INT}(\bar{v}2) \quad \bar{b}1 = \text{false}}{\text{floordiv}([v2, v1]) = \text{ERR}(s)}$$
$$\frac{\text{getValue}(v1) = \text{BOOL}(\bar{b}1) \quad \text{getValue}(v2) = \text{INT}(\bar{v}2) \quad \bar{b}1 = \text{true} \quad v' = v2}{\text{floordiv}([v2, v1]) = \text{INT}(v')}$$

Fig. 4. Formalization for the built-in type int



Safety

- Proving safety (or soundness) of our typing system entails proving that well-typed terms do not reach a *stuck state*, which is a state where no formal semantics rule is applicable [Pierce 2002].

THEOREM 3.3 (FRAME STACK SEMANTIC PROGRESS). *A well-typed frame stack does not get stuck, that is, it is either in a final state or it can take a step according to the frame stack semantic rules.*

LEMMA 3.2 (FRAME SEMANTIC PROGRESS). *A well-typed frameObj does not get stuck, that is, it is either in a return state or it can take a step according to the frame semantics rules.*

THEOREM 3.4 (PRESERVATION). *If a frame $f : \text{frameObj}$ evaluates to f' , then $f' : \text{frameObj}$.*



Formal Verification

- Py* implements these rules using one function for each bytecode instruction.
- These functions take as input the relevant frame components, and return the updated components.
- We deduce pre and post-conditions from the formal semantic rules:
 - Force them through the use of F*'s dependent typing system and Z3 (F*'s automated theorem prover).
- Example:

$$\frac{}{\langle \varphi, \Gamma, i, \beta, v :: \Delta \rangle \xrightarrow{\Gamma.\Pi[i]=\text{DUP_TOP}} \langle \varphi, \Gamma, i + 1, \beta, v :: v :: \Delta \rangle}$$

```
let dup_top datastack = (hd datastack)::datastack
```

```
val dup_top: (l:list pyObj {Cons? l}) -> Tot (l2:list pyObj {l2 == (hd l)::l})
```



Discussion



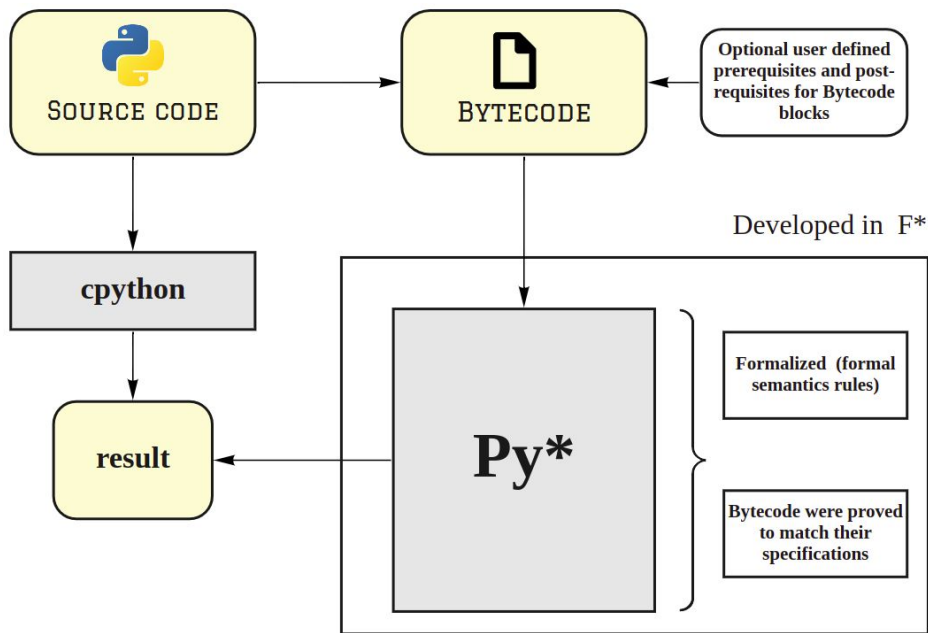
Py* is a Reference

- The semantics of Py* could be used as a **reference** for other Python interpreter **implementations**.
- The techniques used for **formal verification** can be used by other **virtual machines** formalization projects.



Finding bugs in other interpreters

- Py* could be used to find bugs in other Python interpreters.
- By running valid random Python code in Py* and other Python interpreters then observing results that don't match.
- We built an automated testing pipeline that we used for testing Py*, and we plan on extending it with comparisons with other VMs.





Improvements

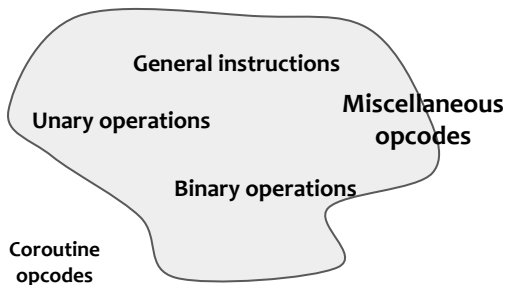
- We expect executing Speed to be lower than cpython.
 - Abstracting Imperative concepts in a functional environment is costly (E.g., hash tables).
- Could be solved by developing Py* in **Low*** instead of F*.
 - Low* have imperative concepts and code written in it can be translated into C code.
 - However, reasoning and formalizing such a thing will be much more difficult.



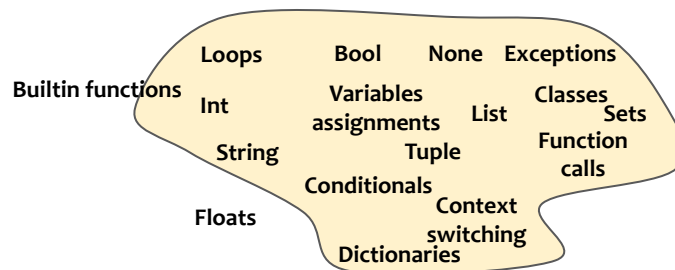
Progress

- Defined formal semantics rules, implemented, formally verified, and extracted OCaml code for the following instructions within the shaped below.

Bytecode instructions



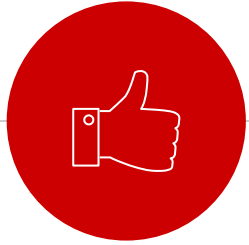
Python Source Code





Future Work

- Support the rest of the bytecode instructions.
- Extend our test-suite to include all cpython's test-suite.
- Use the automatic testing pipeline to verify the correctness of different Python interpreters.



Thanks!

Any questions?